

of carrying said wafers under vacuum in a vacuum-tight carrier comprising a body including sidewalls and also a cover closeable to make a vacuum-tight seal with said body, said sidewalls each having plural ledges thereon defining slots to hold wafers of a predetermined size, said ledges on said sidewalls having at least one surface thereof sloped to be at least 5 degrees out of parallel with the plane of said slots; said carrier further comprising an elastic element on an inner surface thereof, said elastic element holding wafers of said predetermined size secure against free movement.

Brief Summary Text - BSTX (44):

According to the present invention there is provided: a method of transporting integrated circuit wafers during fabrication, comprising the steps of: carrying said wafers under vacuum in a vacuum-tight carrier comprising a body including sidewalls and also a cover closeable to make a vacuum-tight seal with said body, said sidewalls each having plural ledges thereon defining slots to hold wafers of a predetermined size, said ledges on said sidewalls having at least one surface thereof sloped to be at least 5 degrees out of parallel with the plane of said slots; said carrier further comprising an elastic element on an inner surface thereof, said elastic element holding wafers of said predetermined size secure against free movement.

Brief Summary Text - BSTX (45):

According to the present invention there is provided: a method of fabricating integrated circuits, comprising the steps of: transporting integrated circuit wafers during fabrication, comprising the steps of: carrying said wafers under vacuum in a vacuum-tight carrier comprising a body including sidewalls and also a cover closeable to make a vacuum-tight seal with said body, said sidewalls each having plural ledges thereon defining slots to hold wafers of a predetermined size, said ledges on said sidewalls having at least one surface thereof sloped to be at least 5 degrees out of parallel with the plane of said slots; said carrier further comprising an elastic element on an inner surface thereof, said elastic element holding wafers of said predetermined size secure against free movement.

Detailed Description Text - DETX (16):

The transfer arm 28 preferably has two degrees of freedom. One direction of motion permits the transfer arm 28 to reach into carrier 10 or through port 30 into the adjacent processing chamber. The other degree of freedom corresponds to vertical motion of the transfer arm 28, which permits selection of which wafer inside the carrier 10 is to be removed, or which slot a wafer is to be placed into.

Detailed Description Text - DETX (19):

In the presently preferred embodiment, a linkage is used inside the rotatable transfer arm support 44, to permit the transfer arm 28 to move very compactly. The transfer arm support 44 is preferably connected to a rotating rod which is driven by the arm drive motor 34, but the arm support 44 is preferably mounted on a tubular support 46 which does not rotate. An internal chain and sprocket linkage is preferably used so that the joint between arm support 44 and transfer arm 28 moves with twice the angular velocity of the joint between arm support 44 and tubular support 46. (Of course, many other mechanical linkages could alternatively be used to accomplish this.) This means that, when the arm support 44 is in its home position, a supported wafer 48 will be approximately above the tubular support 46, but when the arm support 44 is rotated 90 degrees with respect to the tubular support 46, the transfer arm 28 will have been rotated 180 degrees with respect to the arm support 44, so

U.S. Patent Oct. 30, 1990 Sheet 8 of 8 4,966,519

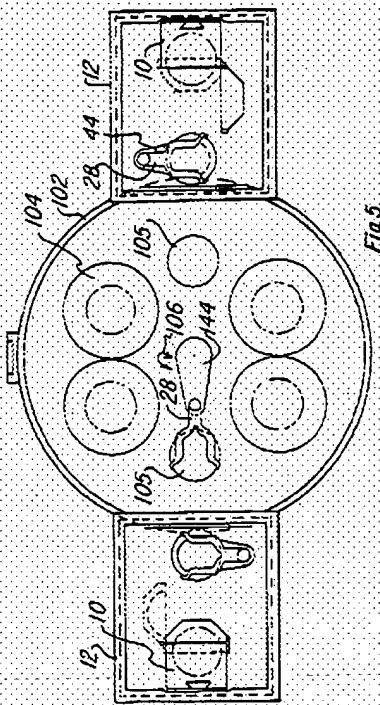


Fig. 5

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US-PAT-NR: 6199927

DOCUMENT-IDENTIFIER: US 6199927 B1

TITLE: Robot blade for handling of semiconductor substrates

— KWIC —

Brief Summary Text - BSTX (5):

Semiconductor processing has been automated in recent years, to provide both efficiency in processing steps and to avoid contamination of the semiconductor substrate which might otherwise occur. As a part of this automation, semiconductor substrates, typically thin wafers, are frequently stored in cassettes to await further processing. In the most commonly used cassette designs, the wafers are horizontally oriented within the cassette with minimal spacing between each wafer. To place the wafers within the cassette and remove them without damage to or contamination of the wafers requires the use of specially designed robot-aided wafer handling equipment.

Brief Summary Text - BSTX (6):

U.S. Pat. No. 4,630,738 to Schwartz et al., Issued Nov. 4, 1986 describes a vacuum pick suitable for removing semiconductor wafers from and replacing wafers in a cassette holder. The vacuum pick includes a thin profile housing having a wafer support surface with a cavity therein, a resilient, flexible member covering a portion of the cavity to form an enclosure, and a rigid chuck mounted on the flexible member to permit movement of the chuck relative to the housing. Vacuum is applied to the enclosure so the wafer and the chuck are retracted against the housing and held firmly in place.

Detailed Description Text - DETX (3):

Generally, the substrate handling apparatus obtains the substrate from one location and transfers it to another within the processing system. FIG. 10A illustrates a three dimensional view of a known batch heating cassette 10 used for large substrates 32 of the kind used in the fabrication of liquid crystal displays. FIG. 10B shows a cross-sectional view of the cassette 10 illustrated in FIG. 10A, with the substrates 32 in place upon heating shelves 33 within the cassette 10. These Figures illustrate the close spacing between the stored semiconductor substrates 32 within the cassette 10. With reference to FIGS. 10A and 10B, a typical heating cassette 10 comprises sidewalls 12 and 14, and a bottom wall 16. A lid 18 is fastened to the top of the sidewalls 12 and 14. Additional side walls 13 and 15 close opposing ends of sidewalls 12 and 14. Sidewall 13, adjacent system chamber 50 is fitted with a slit valve 11 through which the substrate 32 can be transferred into and out of the cassette 10, in the direction indicated by the arrow 64.

US Reference Patent Number - URPN (4):

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US Reference Patent Number - URPN (6):

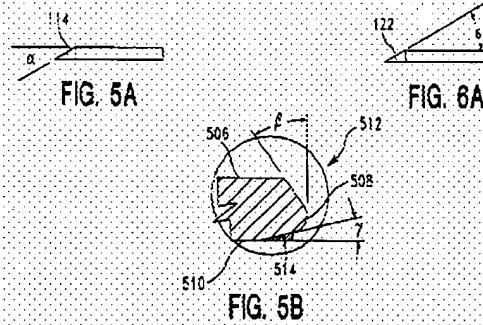
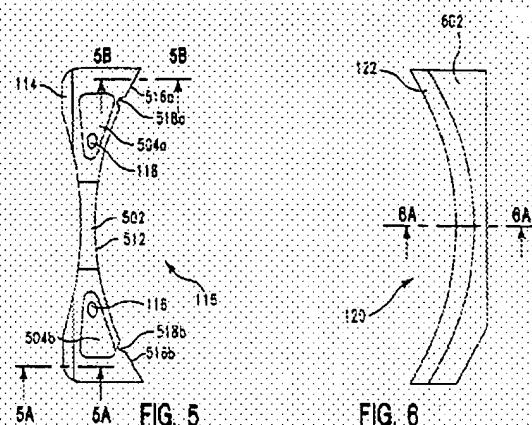
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U.S. Patent Mar. 13, 2001 Sheet 3 of 6 US 6,199,927 B1

Mar. 13, 2001

Sheet 3 of 6

U.S. 6,199,927.81



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US-PAT-NO: 5425611

DOCUMENT-IDENTIFIER: US 5425611 A

TITLE: Substrate handling and processing system

U.S. Patent

June 20, 199

Sheet 5 of 5

5,425,611

— RWI

Brief Summary Text - BSTX (4):

In U.S. Pat. Nos. 4,311,122 and 4,749,465, similar vacuum processing systems are disclosed wherein individual substrates are processed while in a common vacuum environment. In the noted patents, as in many coating systems which employ a substrate transport system, the various fixed and moving parts of the transport system frequently become at least partially coated incidentally along with the substrate. The flaking of deposited material from the transport system, especially from the moving parts, leads to the generation of particulates which may be detrimental to the substrates. This leads to the need for frequent, and sometimes extensive, servicing of the noted substrate transport systems.

Detailed Description Text - DETX (11)

The lift blades 11, 12 are guided for movement up and down in a vertical path intersecting the conveyor system 1 at right angles. The width of the blades 11, 12 is less than that of the spacing between the main walls of the cassette 2 which hold the substrates. The blades 11, 12 are also thinner than the spacing between adjacent substrates retained in the cassette 2.

US Reference Patent Number - URPN (2):

4500437

US Reference Group - URGP (2):

9300432 19850200 Boys et al. 414/217

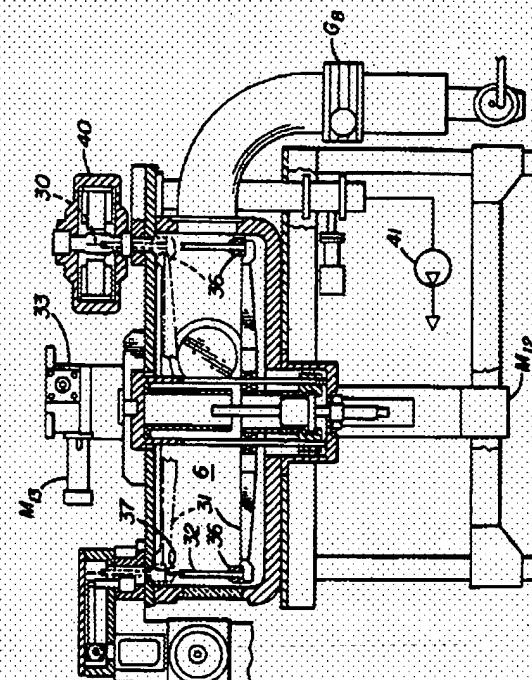


FIGURE 5

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